LaPlace TransformsECE 341: Random Processes

Lecture #10

note: All lecture notes, homework sets, and solutions are posted on www.BisonAcademy.com

Transfer Functions and Differential Equations:

LaPlace transforms assume all functions are in the form of

$$
y(t) = \begin{cases} a \cdot e^{st} & t > 0 \\ 0 & otherwise \end{cases}
$$

This results in the derivative of y being:

$$
\frac{dy}{dt} = s \cdot y(t)
$$

This lets you convert differential equations into transfer funcitons and back.

Example 1: Find the transfer function from X to Y

$$
\frac{d^3y}{dt^3} + 6\frac{d^2y}{dt^2} + 11\frac{dy}{dt} + 6y = 8\frac{dx}{dt} + 10x
$$

Solution: Substitute 's' for *ddt*

$$
s^3Y + 6s^2Y + 11sY + 6Y = 8sX + 10X
$$

Solve for Y

$$
(s3 + 6s2 + 11s + 6)Y = (8s + 10)X
$$

$$
Y = \left(\frac{8s + 10}{s3 + 6s2 + 11s + 6}\right)X
$$

The transfer function from X to Y is

$$
G(s) = \left(\frac{8s+10}{s^3+6s^2+11s+6}\right)
$$

• Note: The transfer function is often called 'G(s)' since it is the gain from X to Y.

Example 2: Find the differential equation relating X and Y

$$
Y = \left(\frac{8s + 10}{s^3 + 6s^2 + 11s + 6}\right)X
$$

Cross multiply:

 $(s^3$ $3+6s^2$ $(X^2 + 11s + 6)Y = (8s + 10)X$

Note that 'sY' means 'the derivative of Y'

$$
\frac{d^3y}{dt^3} + 6\frac{d^2y}{dt^2} + 11\frac{dy}{dt} + 6y = 8\frac{dx}{dt} + 10x
$$

Sidelight: Fractional powers are not allowed in transfer functions.

- $s²Y$ means 'the second derivative of Y'. *Y*
- $s^{2.3}Y$ means 'the 2.3th derivative of Y'. *Y*

I have no idea what a 0.3 derivative is.

Solving Transfer Functions with Sinusoidal Inputs

Example 3: Find y(t) given

$$
Y = \left(\frac{8s+10}{s^3+6s^2+11s+6}\right)X
$$

and

 $x(t) = 3 \cos(4t)$

Solution: From Euler's identity:

$$
e^{j4t} = \cos(4t) + j\sin(4t)
$$

(a+jb) $e^{j4t} = (a\cos(4t) - b\sin(4t)) + j(\cdot)$
a+jb \leftrightarrow $a\cos(4t) - b\sin(4t)$

- real = cosine
- $-$ imag = sine

Take the real part and you the sine wave.

$$
s = j4
$$

$$
X = 3 + j0
$$

Convert to phasors

$$
Y = \left(\frac{8s+10}{s^3+6s^2+11s+6}\right)X
$$

\n
$$
Y = \left(\frac{8s+10}{s^3+6s^2+11s+6}\right)_{s=j4}(3+j0)
$$

\n
$$
Y = (-0.191-j0.315)(3+j0)
$$

\n
$$
Y = -0.544-j0.946
$$

meaning

y(*t*)=[−]0.544 cos(4*t*)+ 0.946 sin (4*t*)

Example 4: Find y(t) if $x(t) = 5\cos(20t) + 6\sin(20t)$

Solution:

$$
Y = \left(\frac{8s+10}{s^3+6s^2+11s+6}\right)_{s=j20} (5-j6)
$$

\n
$$
Y = (-0.019-j0.005)(5-j6)
$$

\n
$$
Y = -0.123+j0.092
$$

meaning

$$
y(t) = -0.123 \cos(20t) - 0.092 \sin(20t)
$$

Note that the gain varies with frequency (i.e. this is a filter).

Example 5: Find $y(t)$ if

 $x(t) = 3\cos(4t) + 5\cos(20t) + 6\sin(20t)$

Solution: Treat this as two separate problems

- $x(t) = 3 \cos(4t)$
- $x(t) = 5 \cos(20t) + 6 \sin(20t)$

The total input is the sum of the two $x(t)$'s. The total output is the sum of the two $y(t)$'s

> *y*(*t*)=[−]0.544 cos(4*t*)+ 0.946 sin (4*t*)[−]0.123 cos(20*t*)0.092 sin (20*t*)

Solving Transfer Functions with Step Inputs

Example: Find the impulse response of

$$
G(s) = \left(\frac{5}{s+3}\right)
$$

Solution: Translating:

$$
Y = \left(\frac{5}{s+3}\right)X
$$

$$
Y = \left(\frac{5}{s+3}\right)(1)
$$

From the above table:

$$
y(t) = 5e^{-3t}u(t)
$$

Example: Find the step response of

$$
G(s) = \left(\frac{5}{s+3}\right)
$$

Solution: Translating:

$$
Y = \left(\frac{5}{s+3}\right)\left(\frac{1}{s}\right) = \left(\frac{5}{s(s+3)}\right)
$$

Do a partial fraction expansion

$$
Y = \left(\frac{5}{s(s+3)}\right) = \left(\frac{A}{s}\right) + \left(\frac{B}{s+3}\right)
$$

$$
Y = \left(\frac{5}{s(s+3)}\right) = \left(\frac{5/3}{s}\right) - \left(\frac{5/3}{s+3}\right)
$$

Using the above table for each term:

$$
y(t) = \left(\frac{5}{3} - \frac{5}{3}e^{-3t}\right)u(t)
$$

Repeated Roots

Find the step response of

$$
Y = \left(\frac{1}{\left(s+1\right)^2}\right)X
$$

Solution: Use the table or change the problem

$$
Y = \left(\frac{1}{(s+1.01)(s+0.99)}\right)X
$$

There are no longer repeated roots

The differential equation is almost identical

- It's just a model for a real system
- No model is perfect
- The odds of two poles being *exactly* the same is almost zero

Solving with Complex Roots:

$$
\left(\frac{a\angle\theta}{s+b+jc}\right) + \left(\frac{a\angle-\theta}{s+b-jc}\right) \Rightarrow 2a \cdot e^{-bt}\cos(ct-\theta)u(t)
$$

Example: Find the y(t) given that

$$
Y(s) = G \cdot U = \left(\frac{15}{s^2 + 2s + 10}\right) \cdot \left(\frac{1}{s}\right)
$$

Solution: Factoring Y(s)

$$
Y(s) = \left(\frac{15}{(s)(s+1+j3)(s+1-j3)}\right)
$$

Using partial fraction expansion:

$$
Y(s) = \left(\frac{1.5}{s}\right) + \left(\frac{0.7906\angle -161.56^0}{s+1+j3}\right) + \left(\frac{0.7906\angle 161.56^0}{s+1-j3}\right)
$$

$$
y(t) = 1.5 + 1.5812 \cdot e^{-t} \cdot \cos(3t + 161.56^0) \qquad \text{for } t > 0
$$

Properties of LaPlace Transforms

Linearity: $aF(s) + bG(s)$

Convolution: $f(t) * *g(t) \Leftrightarrow F(s) \cdot G(s)$

Differentiation:

$$
\frac{dy}{dt} \Longleftrightarrow sY - y(0)
$$

$$
\frac{d^2y}{dt^2} \Longleftrightarrow s^2Y - sy(0) - \frac{dy(0)}{dt}
$$

 $\frac{1}{2}X(s)$

Integration:

$$
\int_0^t x(\tau)d\tau = \frac{1}{s} X(s)
$$

Delay*x*(*t*−*T*)⇔*e*−*s T*

Proofs

Linearity:

$$
L(af(t) + bg(t)) = \int_{-\infty}^{\infty} (af(t) + bg(t)) \cdot e^{-st} \cdot dt
$$

=
$$
\int_{-\infty}^{\infty} (af(t)) \cdot e^{-st} \cdot dt + \int_{-\infty}^{\infty} (bg(t)) \cdot e^{-st} \cdot dt
$$

=
$$
a \int_{-\infty}^{\infty} f(t) \cdot e^{-st} \cdot dt + b \int_{-\infty}^{\infty} g(t) \cdot e^{-st} \cdot dt
$$

=
$$
aF(s) + bG(s)
$$

Convolution:

$$
f(t) * * g(t) = \int_{-\infty}^{\infty} f(t - \tau) \cdot g(\tau) \cdot d\tau
$$

\n
$$
L(f(t) * * g(t)) = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} f(t - \tau) \cdot g(\tau) \cdot d\tau \right) \cdot e^{-st} \cdot dt
$$

\n
$$
= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} f(t - \tau) \cdot g(\tau) \cdot e^{-st} \cdot dt \right) \cdot d\tau
$$

$$
= \left(\int_{-\infty}^{\infty} f(t-\tau) \cdot e^{-st} \cdot dt\right) \cdot \left(\int_{-\infty}^{\infty} g(t) \cdot e^{-st} \cdot dt\right)
$$

$$
= F(s) \cdot G(s)
$$

Differentiation:

$$
L\left(\frac{dx}{dt}\right) = \int_{-\infty}^{\infty} \left(\frac{dx(t)}{dt}\right) \cdot e^{-st} \cdot dt
$$

Assume causal (zero for t<0)

$$
L\left(\frac{dx}{dt}\right) = \int_0^\infty \left(\frac{dx(t)}{dt}\right) \cdot e^{-st} \cdot dt
$$

Integrate by parts.

$$
(ab)' = a' \cdot b + a \cdot b'
$$

$$
\int a' \cdot b \cdot dt = ab - \int a \cdot b' \cdot dt
$$

Let

$$
a' = \frac{dx}{dt}
$$

$$
a = x
$$

$$
b = e^{-st}
$$

then

$$
L\left(\frac{dx}{dt}\right) = \int_0^\infty \left(\frac{dx(t)}{dt}\right) \cdot e^{-st} \cdot dt
$$

= $(x \cdot e^{-st})_0^\infty - \int_{-\infty}^\infty -s \cdot x(t) \cdot e^{-st} \cdot dt$
= $-x(0) + s \int_{-\infty}^\infty x(t) \cdot e^{-st} \cdot dt$
= $sX - x(0)$

Integration:

$$
L\left(\int_0^t x(\tau) \cdot d\tau\right) = \int_{-\infty}^{\infty} \left(\int_0^t x(\tau) \cdot d\tau\right) \cdot e^{-st} \cdot dt
$$

Integrate by parts.

$$
\int a \cdot b' \cdot dt = ab - \int a' \cdot b \cdot dt
$$

Let

$$
a = \int_0^t x(\tau) \cdot d\tau
$$

$$
b' = e^{-st}
$$

then

$$
a' = x
$$

\n
$$
b = \frac{-1}{s}e^{-st}
$$

\n
$$
L\left(\int_0^t x(\tau) \cdot d\tau\right) = \int_{-\infty}^{\infty} \left(\int_0^t x(\tau) \cdot d\tau\right) \cdot e^{-st} \cdot dt
$$

$$
= \left(\int_0^t x(\tau) \cdot d\tau \cdot \frac{-1}{s} e^{-st}\right)_{-\infty}^{\infty} - \int_{-\infty}^{\infty} x \cdot \frac{-1}{s} e^{-st} \cdot dt
$$

Assuming the function vanishes at infinity

$$
= \frac{1}{s} \int_{-\infty}^{\infty} x \cdot dt
$$

$$
= \left(\frac{1}{s}\right) X(s)
$$

Time Delay

$$
L(x(t-T)) = \int_{-\infty}^{\infty} x(t-T) \cdot e^{-st} \cdot dt
$$

Do a change of variable

$$
t - T = \tau
$$

\n
$$
L(x(t - T)) = \int_{-\infty}^{\infty} x(\tau) \cdot e^{-s(\tau + T)} \cdot d\tau
$$

\n
$$
= \int_{-\infty}^{\infty} x(\tau) \cdot e^{-s\tau} \cdot e^{-sT} \cdot d\tau
$$

\n
$$
= e^{-sT} \cdot \int_{-\infty}^{\infty} x(\tau) \cdot e^{-s\tau} \cdot d\tau
$$

\n
$$
= e^{-sT} \cdot X(s)
$$

Summary

LaPlace transforms

- Turn differential equations into algebraic equations
- Turn convolution in to multiplication
- They are very useful in solving differential equations
	- i.e. Analog Signals
	- Multiplications is easier than convolution
- They will also be useful in Random Processes
	- If we ever need to convolve continuous pdf's, LaPlace transforms will turn thisinto multiplication
	- In statistics, LaPlace transforms are termed *moment generating functions*