

Active Filters

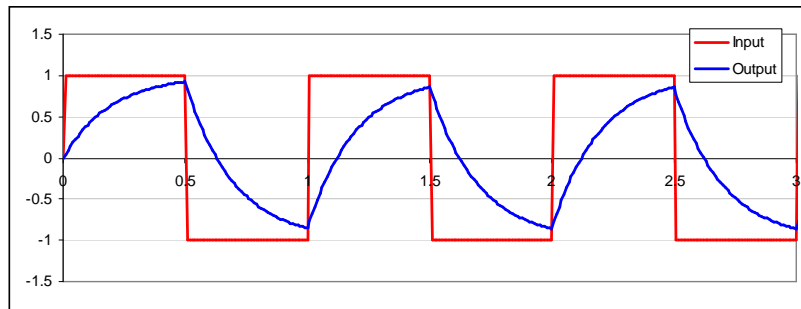
Background:

Filters are circuits whose behaviour changes with frequency. Essentially, all circuits with capacitors and/or inductors are filters.

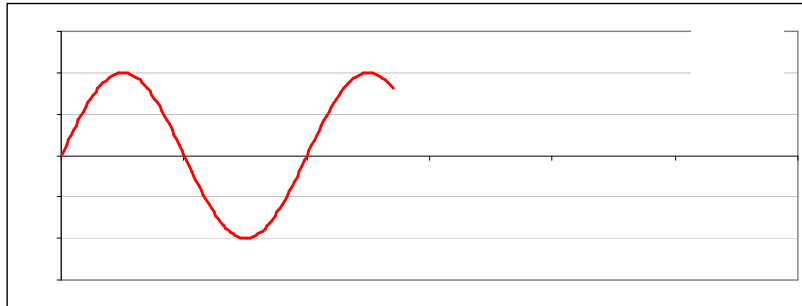
When analyzing a filter, sinusoids are used for inputs and outputs. Sinusoids are very special signals. For example, assume you apply a 1Hz signal to an RC filter which satisfies the following differential equation

$$\frac{dy}{dt} + 5y = 5x$$

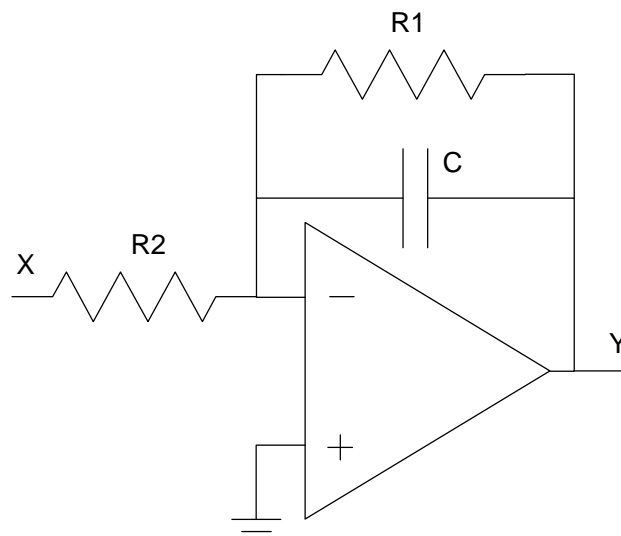
where y is the output of the RC filter and x is the input. If the input is a 1Hz square wave, the output will not be a square wave. The relationship between the two is simple one.



If the input is a 1Hz sine wave, however, the output is also a 1Hz sine wave.



Real Poles, No Zeros (take 2)



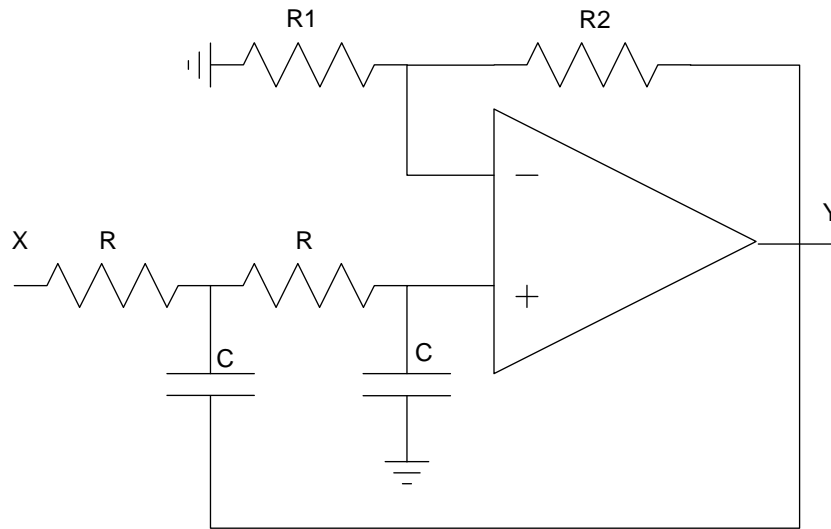
$$Y = \frac{a}{s+b} X$$

where

$$a = \frac{1}{R_2 C}$$

$$b = \frac{1}{R_1 C}$$

Complex Poles, No Zeros



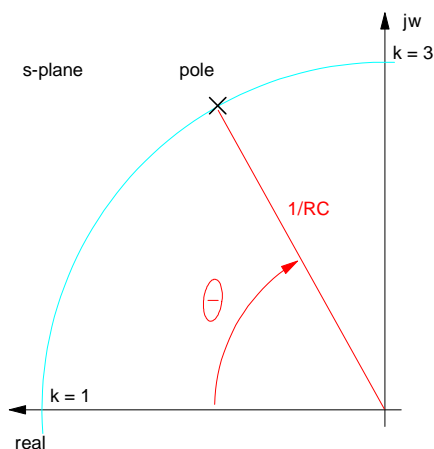
$$Y = \frac{k \times \frac{1}{RC}^2}{s^2 + \frac{3k}{RC} s + \frac{1}{RC}^2} X$$

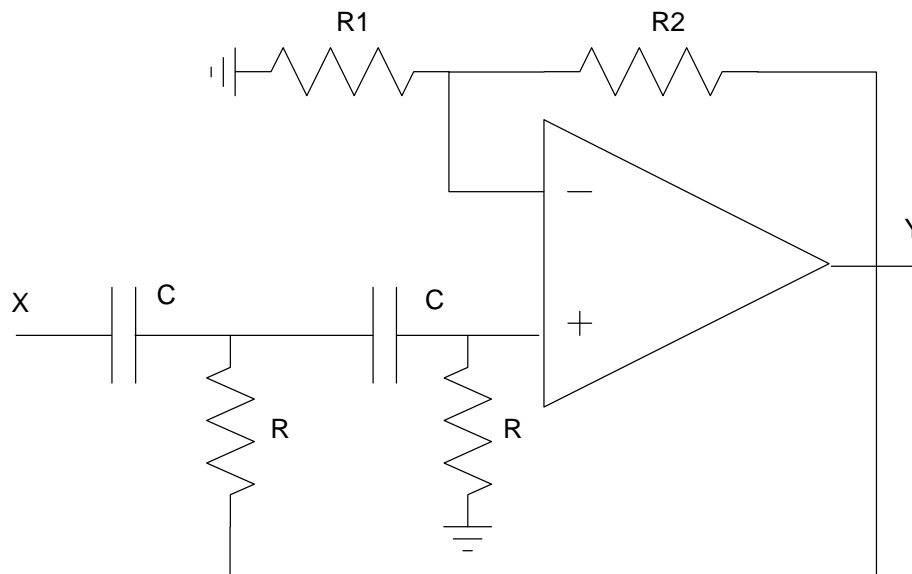
This filter has two complex poles with

- Amplitude = $\frac{1}{RC}$
- Angle: $3 \quad k = 2 \cos$
- DC gain $k = 1 + \frac{R_2}{R_1}$

Note that the angle of the poles goes from

- 0 degrees when $k = 1$
- 90 degrees when $k = 3$ (an oscillator)



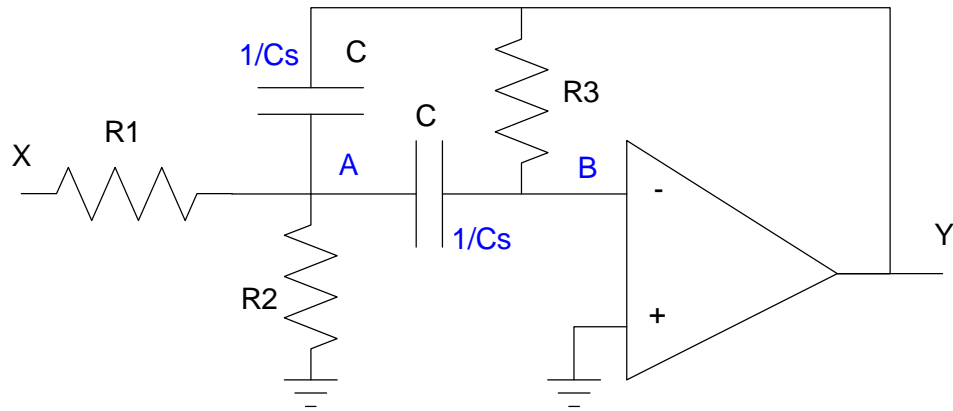
Complex Poles, Two Zeros at $s = 0$ 

$$Y = \frac{k s^2}{s^2 + \frac{3k}{RC} s + \frac{1}{RC}} X$$

This filter has two complex poles with

- Amplitude = $\frac{1}{RC}$
- Angle: $3 k = 2 \cos$
- High Freq gain $k = 1 + \frac{R_2}{R_1}$

Complex Poles, One Zero at $s = 0$: $Y = \frac{as}{s^2+bs+c} X$



$$Y = \frac{\frac{1}{R_1 C} s}{s^2 + \frac{2}{R_3 C} s + \frac{R_1 + R_2}{R_1 R_2} \frac{1}{R_3 C^2}} X$$

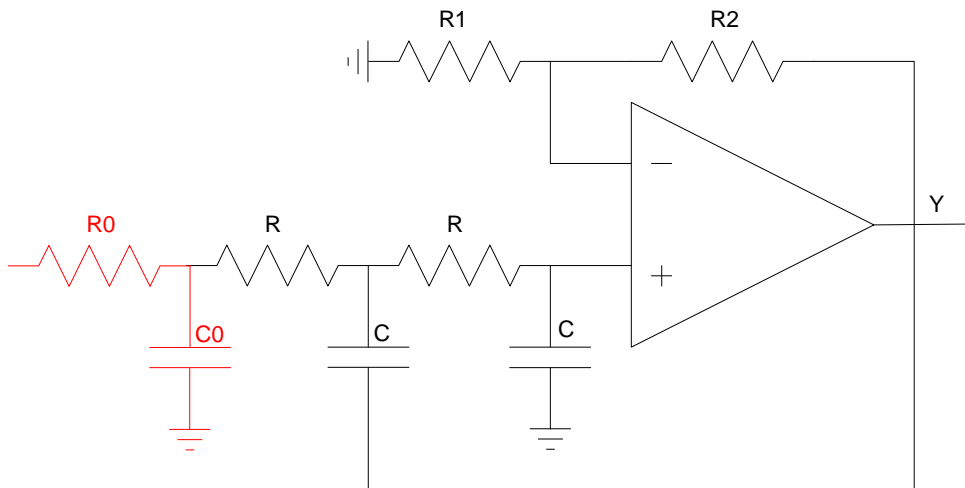
Example: Design a circuit to implement

$$Y = \frac{1,244,485}{(s+85)(s+121 - 69.5^\circ)(s+121 + 69.5^\circ)} X$$

Rewrite this as

$$Y = \frac{85}{s+85} \frac{14,641}{(s+121 - 69.5^\circ)(s+121 + 69.5^\circ)} X$$

Use the previous filters



$$\frac{\frac{1}{R_0 C_0}}{s + \frac{1}{R_0 C_0}} \quad \frac{k \times \frac{1}{RC}^2}{s^2 + \frac{3k}{RC} s + \frac{1}{RC}^2}$$

To avoid loading, let

- R0 = 10k
- R = 100k

Matching terms in the denominator:

$$\frac{1}{R_0 C_0} = 85 \quad C_0 = 1.17 \text{ F}$$

$$\frac{1}{RC} = 121 \quad C = 0.082 \text{ F}$$

$$3k = 2 \cos(69.5^\circ)$$

$$k = 2.3$$

$$1 + \frac{R_2}{R_1} = 2.3$$

$$R_1 = 100k, \quad R_2 = 1.3k$$

Note: This circuit has a DC gain of 2.3 (instead of 1). Just note this and call the output 2.3Y.

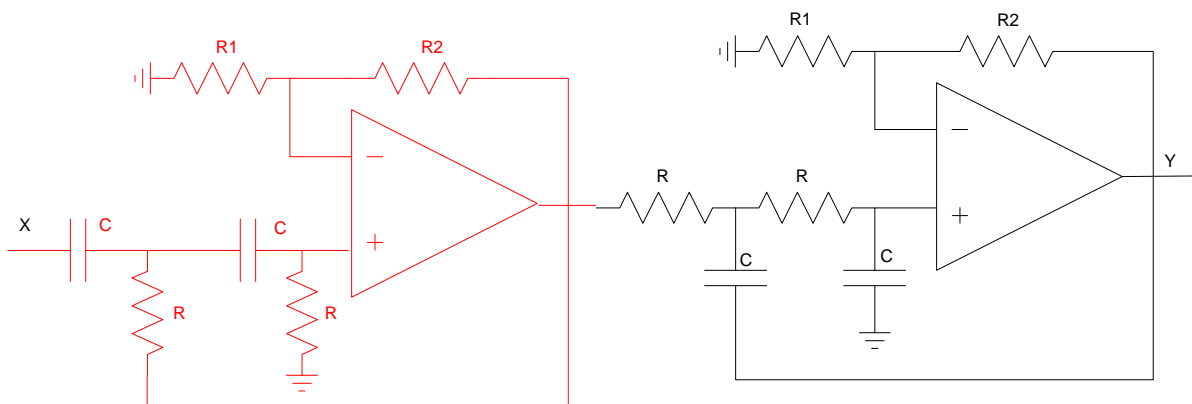
Example: Design a filter to implement

$$Y = \frac{100,000^2}{s^2+14s+100} \frac{1}{s^2+100s+10,000} X$$

Solution: Rewrite this as the product of two filters

$$Y = \frac{s^2}{s^2+14s+100} \frac{10,000}{s^2+100s+10,000} X$$

Using the previous circuits (building blocks),



$$\frac{kx^2}{s^2 + \frac{3k}{RC}s + \frac{1}{RC}^2}$$

$$\frac{kx \frac{1}{RC}^2}{s^2 + \frac{3k}{RC}s + \frac{1}{RC}^2}$$

Matching the poles:

$$\frac{1}{RC}^2 = 100$$

$$R = 100k$$

$$C = 0.1\mu F$$

$$3 \quad k = 2 \cos(45^\circ)$$

$$k = 1.5858$$

$$R1 = 100k$$

$$R2 = 58k$$

$$\frac{1}{RC}^2 = 10,000$$

$$R = 100k$$

$$C = 0.001\mu F$$

$$3 \quad k = 2 \cos(60^\circ)$$

$$k = 2$$

$$R1 = 100k$$

$$R2 = 100k$$

Note: This circuit has a DC gain of 3.17 (instead of 10). Just note this and call the output 3.17Y.

Filter Description	G(s)	Circuit
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Real Poles
No Zeros
DC gain > 1

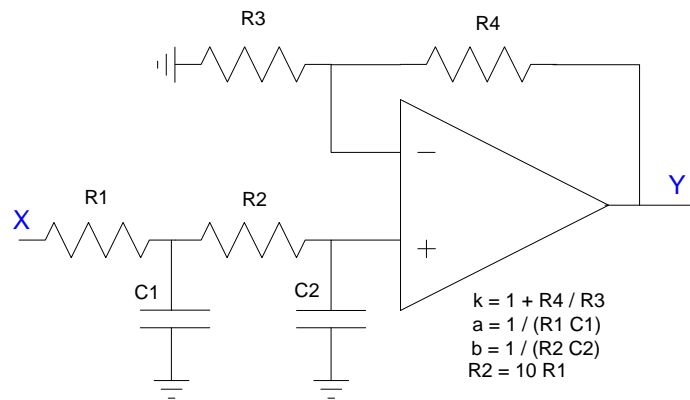
$$\frac{kab}{(s+a)(s+b)}$$

$$a = \frac{1}{R_1 C_1}$$

$$b = \frac{1}{R_2 C_2}$$

$$R_2 = 10R_1$$

$$k = 1 + \frac{R_4}{R_3}$$

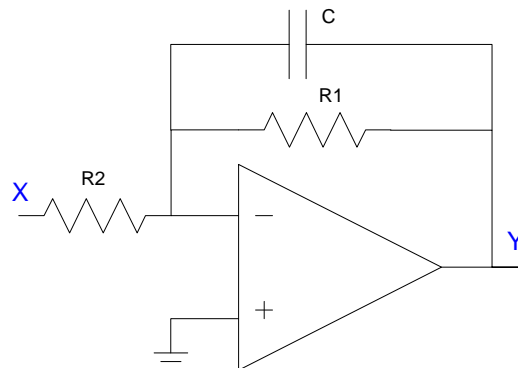


Single Real Pole
No Zeros

$$\frac{a}{s+b}$$

$$b = \frac{1}{R_1 C}$$

$$\frac{a}{b} = \frac{R_1}{R_2}$$



Complex Poles
No Zeros

$$\frac{ka^2}{(s+a)(s+a)}$$

$$a = \frac{1}{RC}$$

$$k = 1 + \frac{R_4}{R_3}$$

$$3 \quad k = 2 \cos$$

